

# Lab2: Fun with system calls

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# Topics for today

- How to add a functional system call?
- Assignments & hints:
  - Change the exit syscall signature to `void exit(int status);`
  - Update the wait syscall to `int wait(int *status);`
  - Add a waitpid syscall: `int waitpid(int pid, int *status, int options);`
  - Write an example program to illustrate your waitpid works.

[1]: XV6 book: <https://pdos.csail.mit.edu/6.828/2014/xv6/book-rev8.pdf>

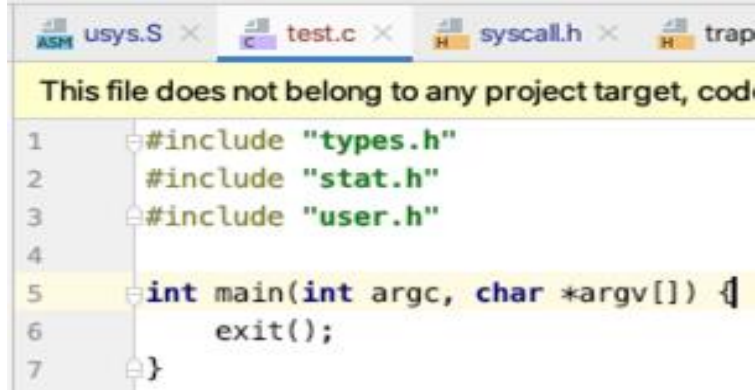
[2]: XV6 syscall explained:

[https://medium.com/@flag\\_seeker/xv6-system-calls-how-it-works-c541408f21ff](https://medium.com/@flag_seeker/xv6-system-calls-how-it-works-c541408f21ff)

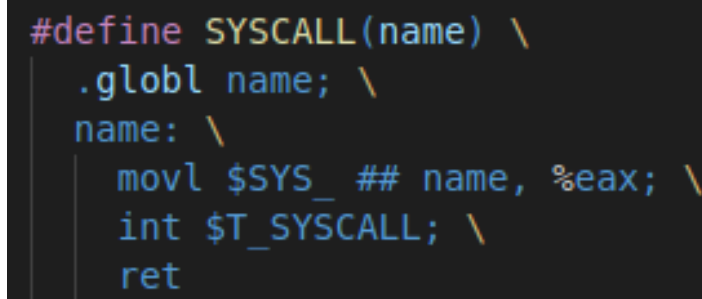
# How does syscall exit() work?

## Step 1: call from user space

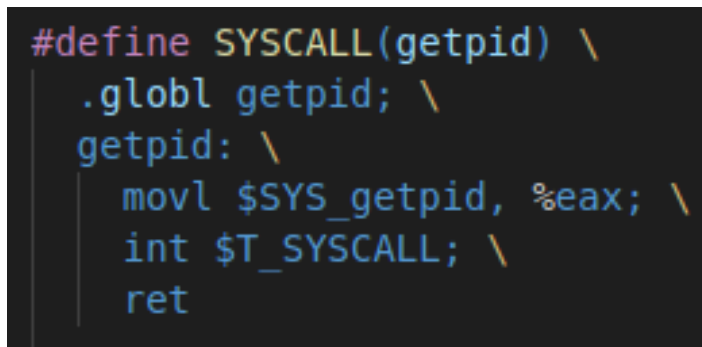
- **test.c**
  - user program to make a syscall
- **user.h**
  - declaration of syscall in user level
- **usys.S**
  - macro definition which in effect as a function
  - move immediate value of `SYS_exit` (defined in `syscall.h`) into register `%eax`;
  - issue interrupt 64 (reserved for all system calls, see `traps.h`)
  - return



```
usys.S x test.c x syscall.h x trap
This file does not belong to any project target, code
1 #include "types.h"
2 #include "stat.h"
3 #include "user.h"
4
5 int main(int argc, char *argv[]) {
6     exit();
7 }
```



```
#define SYSCALL(name) \
    .globl name; \
    name: \
        movl $SYS_ ## name, %eax; \
        int $T_SYSCALL; \
        ret
```



```
#define SYSCALL(getpid) \
    .globl getpid; \
    getpid: \
        movl $SYS_getpid, %eax; \
        int $T_SYSCALL; \
        ret
```

# How does syscall exit() work?

## Step2: transfer to kernel mode

- raise privilege level of CPU to kernel mode
- transfer control to **trap vectors** (initialized in tvinit())
- setup trapframe (see definition in x86.h)
  - **vector.S**
    - push 0 and 64 to stack
    - call alltraps() in trapasm.S
  - **trapasm.S**
    - alltraps() finish trapframe
    - call trap() in trap.c
- **trap()** function
  - set trapframe and call syscall() defined in syscall.c

```
ASM vectors.S x ASM usys.S x C tes
316 jmp alltraps
317 .globl vector64
318 vector64:
319     pushl $0
320     pushl $64
321     jmp alltraps
```

```
C trap.c x ASM vectors.S x ASM usys.S x C test.c
35 // FAULTBREAK: 41
36 void
37 trap(struct trapframe *tf)
38 {
39     if(tf->trapno == T_SYSCALL){
40         if(myproc()->killed)
41             exit();
42         myproc()->tf = tf;
43         syscall();
44         if(myproc()->killed)
45             exit();
46         return;
47     }
```

# How does syscall exit() work?

## Step2: transfer to kernel mode

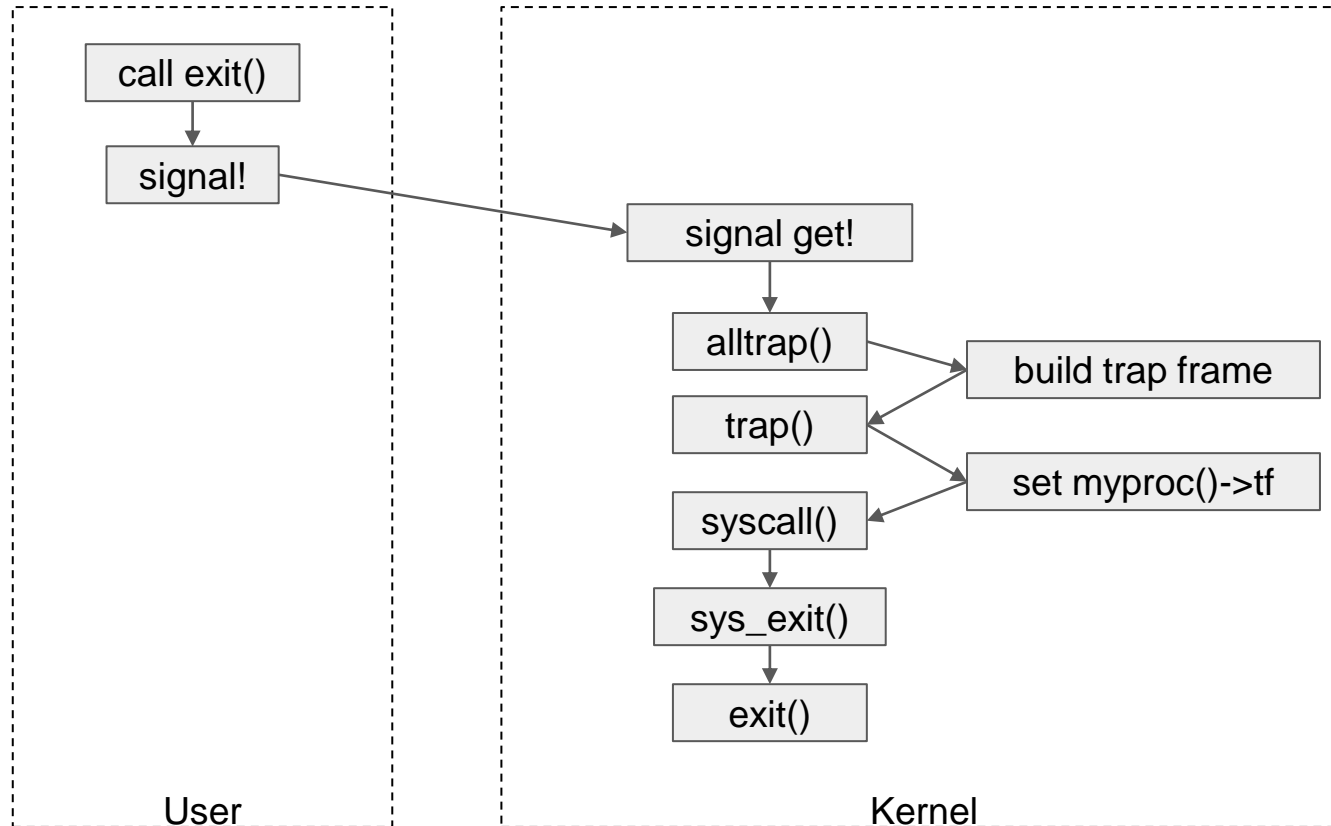
- **syscall() in syscall.c**
  - lookup array of function pointers;
    - `int function(void);`
  - call the `sys_exit` function and put return value in `eax` register.
- **sys\_exit()**
  - implemented in `sysproc.c`
  - helper function `exit()`:
    - defined in `defs.h`
    - implemented in `proc.c`

```
108 static int (*syscalls[])(void) = {
109     [SYS_fork]    sys_fork,
110     [SYS_exit]    sys_exit,
111     [SYS_wait]    sys_wait,
112     [SYS_pipe]    sys_pipe,
113     [SYS_read]    sys_read,
```

```
void
syscall(void)
{
    int num;
    struct proc *curproc = myproc();

    num = curproc->tf->eax;
    if(num > 0 && num < NELEM(syscalls) && syscalls[num]) {
        curproc->tf->eax = syscalls[num]();
    } else {
        cprintf("%d %s: unknown sys call %d\n",
            curproc->pid, curproc->name, num);
        curproc->tf->eax = -1;
    }
}
```

# How exit system call works



# Step-by-step instructions

# Step 1: user application

- Makefile

```
UPROGS=\n    _cat|\n    _echo|\n    _forktest|\n    _grep|\n    _init|\n    _kill|\n    _ln|\n    _ls|\n    _mkdir|\n    _rm|\n    _sh|\n    _stressfs|\n    _usertests|\n    _wc|\n    _zombie|\n    _test|
```

- test.c

```
1  #include "types.h"\n2  #include "stat.h"\n3  #include "user.h"\n4\n5  int main(int argc, char *argv[]) {\n6      //printf(1, "hello world\n");\n7      hello();\n8      exit();\n9  }
```

- user.h

```
23  char* sbrk(int);\n24  int sleep(int);\n25  int uptime(void);\n26  int hello(void);
```



## Step 2

- usys.S

```
28  SYSCALL(getpid)
29  SYSCALL(sbrk)
30  SYSCALL(sleep)
31  SYSCALL(uptime)
32  SYSCALL(hello)
33
```

- syscall.h

```
20  #define SYS_link    19
21  #define SYS_mkdir   20
22  #define SYS_close   21
23  #define SYS_hello   22
```

## Step 3

- syscall.c

```
102  ↗→ extern int sys_unlink(void);  
103  ↗→ extern int sys_wait(void);  
104  ↗→ extern int sys_write(void);  
105  ↗→ extern int sys_uptime(void);  
106  ↗→ extern int sys_hello(void);
```

```
126  [SYS_unlink] sys_unlink,  
127  [SYS_link]   sys_link,  
128  [SYS_mkdir] sys_mkdir,  
129  [SYS_close]  sys_close,  
130  [SYS_hello]  sys_hello,  
131  };
```

## Step 4

- sysproc.c

```
93     int
94     sys_hello(void) {
95         hello();
96         return 0;
97     }
98
```

- proc.c

```
536
537     void
538     hello(void) {
539         cprintf("\n\n Hello from your kernel space! \n\n");
540     }
541
```

- defs.h

```
118     void    sleep(void*, struct spinlock*);
119     void    userinit(void);
120     int     wait(void);
121     void    wakeup(void*);
122     void    yield(void);
123     void    hello(void);
```

# Execute & check the result

```
$ make qemu-nox
```

(... xv6 boots ...)

```
$ test
```

```
$ test
```

```
Hello from your kernel space!
```

## Assignment a) change `exit()` signature to *`void exit(int status)`*

The `exit` system call must act as previously defined (i.e., terminate the current process) but it must also store the exit status of the terminated process in the corresponding structure.

- Modify `proc struct` (`proc.h`) to include a new field that saves an exit status for a terminated process. (e.g. `int exitStatus;`)
- You can either modify existing `exit()` system call in place or define a new system call; note that if you make modifications in place, make sure you modify all locations of `exit()` call in the codebase;
- Modify all relevant files correspondingly;

## Assignment b) update wait() to *int wait(int \*status)*

The wait system call must prevent the current process from execution until any of its child processes is terminated (if any exists) and return the terminated child exit status through the status argument.

- The goal is to get familiar with how to return a value from kernel space to user space;
- Return the terminated child proc's exit status through the status pointer argument;
  - understand the current wait() system call, in terms of how to traverse the ptable to look up for child proc;
  - understand the proc structure;

## Assignment c) add a waitpid() system call

This system call must act like wait system call with the following additional properties:  
The system call must wait for a process (not necessary a child process) with a pid that equals to one provided by the pid argument.

- Hint: This will be a modified version of the original wait() system call. You will need to traverse the ptable to find the proc with pid matches the given pid argument.

## Assignment d) write a testing program

Write an example program to illustrate that your waitpid works. You have to modify the Makefile to add your testing program so that it can be executed from inside the shell once xv6 boots.

- In your report, show the printout of your testing program and illustrate why this printout proves the correctness of your implementation.



## To help finish lab 2 tasks:

- check out existing syscalls with parameters and return value;
- chapter 0-3 of xv6 book (<https://pdos.csail.mit.edu/6.828/2014/xv6/book-rev8.pdf>)